

1 Hyperelastics.jl: A Julia package for hyperelastic 2 material modelling

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5 Summary

6 Hyperelastics.jl is a Julia ([Bezanson et al., 2017](#)) implementation for the largest (70+)
7 collection of hyperelastic material models in existence. The package provides a set of analytical
8 and data-driven strain energy density functions (SEDF) and the tools required to calibrate the
9 models to material tests. The package is designed to leverage multiple-dispatch to define a
10 common set of functions for calculating the SEDF, Second Piola Kirchoff stress tensor, and the
11 Cauchy stress tensor. The package provides: 1) a material model library that is AD compatible
12 and 2) a set of extensible methods for easily defining and testing new material models. The
13 package leverages the `ContinuumMechanicsBase.jl` package for defining the continuum scale
14 quantities and their corresponding relationships.

Statement of need

15 The development of `Hyperelastics.jl` began as a study of the accuracy for a variety of material
16 models for a set of experimental data. Often, researchers rely on custom implementations
17 of material models and the data fitting process to find material parameters that match their
18 experimental data. Hyperelastic models can well represent the nonlinear stress-deformation
19 behavior of many biological tissues as well as engineering polymeric materials.

20 The SEDFs included in this package cover most (if not all) of the available analytical models
21 from the literature to date, from constitutive to phenomenological models. Furthermore, a
22 selection of data-driven models are included as a starting point for the development of new
23 methods.

24 `Hyperelastics.jl` is part of a spinoff Multi-Scale Material Modelling (M^3) Suite being
25 developed by Vagus LLC (www.vagusllc.com), as a byproduct result of ongoing multi-
26 functional material research being carried out in the Translational Robotics and Controls
27 Engineering Research (TRACER) Lab at Liberty University. A pure Julia implementation allows
28 for the use of automatic differentiation (AD) packages to calculate the partial derivatives of the
29 SEDF. `Hyperelastics.jl` is designed to leverage multiple-dispatch to define a common set of
30 functions for calculating the SED, Second Piola Kirchoff Stress Tensor, and the Cauchy Stress
31 Tensor. The package provides a set of hyperelastic models and an interface to `Optimization.jl`
32 for fitting model parameters.

33 Currently, most commercial finite element codes only offer a limited number, often less than
34 10, of hyperelastic models which limits the extent to which researchers are able to accurately
35 model a given material. The closest project to `Hyperelastics.jl` is the `matADi` project by
36 Andreas Dutzler ([Dutzler, 2023](#)) which has AD support for 18 material models.

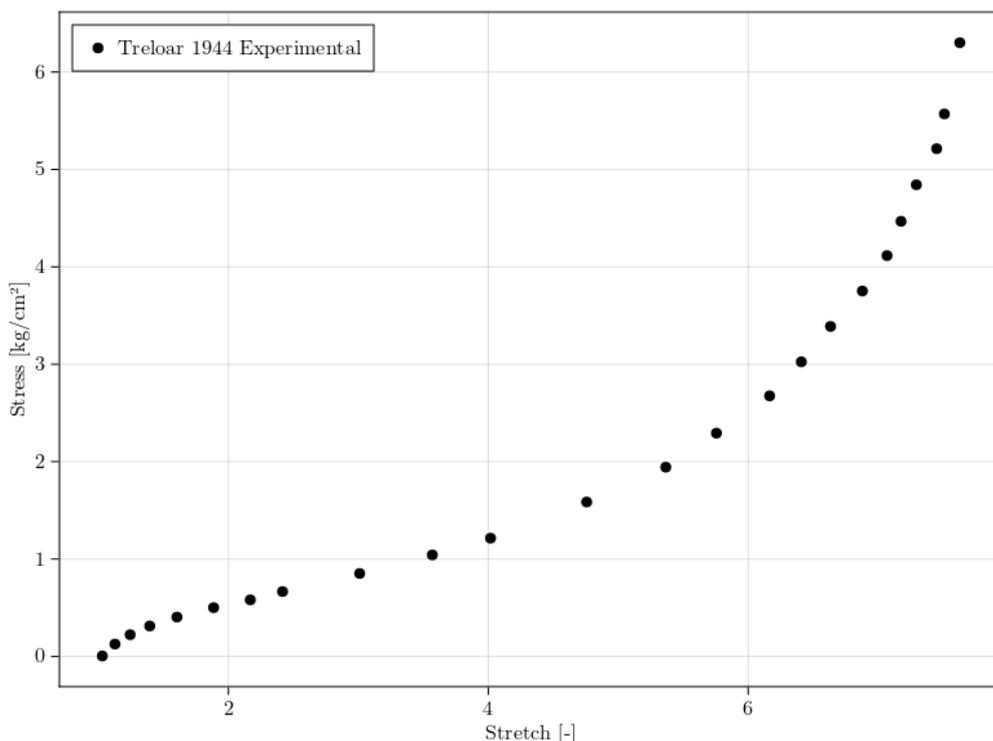
38 **Short Example with Code**

39 For commonly used datasets in hyperelastic modelling, such as the Treloar1944Uniaxial data
40 (Treloar, 1943), functions are available for getting the datasets:

```

using Hyperelastics
using Optimization, OptimizationOptimJL
using ComponentArrays: ComponentVector
using ForwardDiff
using CairoMakie, MakiePublication
set_theme!(theme_web(width = 800))
f = Figure()
ax = Axis(f[1,1])
treloar_data = Treloar1944Uniaxial()
scatter!(ax,
    getindex.(treloar_data.data.λ, 1),
    getindex.(treloar_data.data.s, 1),
    label = "Treloar 1944 Experimental",
    color = :black
)
axislegend(position = :lt)

```



41

42 Multiple dispatch is used on the corresponding function to calculate the values. Based
43 on the model passed to the function, the correct method will be used in the calculation.
44 StrainEnergyDensity, SecondPiolaKirchoffStressTensor, and CauchyStressTensor accept the
45 deformation state as either the principal components in a vector, $[\lambda_1, \lambda_2, \lambda_3]$ or as the
46 deformation gradient matrix, F_{ij} . The returned value matches the type of the input. Parameters
47 are accessed by field allowing for structs, NamedTuples, or other field-based data-types such
48 as those in ComponentArrays.jl and LabelledArrays.jl. For example, the NeoHookean model is
49 accessed with:

```

ψ = NeoHookean()
λ_vec = [2.0, sqrt(1/2), sqrt(1/2)]
p = (μ = 10.0, )
W = StrainEnergyDensity(ψ, λ_vec, p)

50 or

F = rand(3,3)
p = (μ = 20.0, )
W = StrainEnergyDensity(ψ, F, p)

51 A method for creating an OptimizationProblem compatible with Optimization.jl is provided.
52 To fit the NeoHookean model to the Treloar data previously loaded, an additional field-
53 indexed array is used as the initial guess to HyperelasticProblem. It is recommended to use
54 ComponentArrays.jl for optimization of model parameters.

prob = HyperelasticProblem(
    ψ,
    treloar_data,
    ComponentVector(μ = 0.2),
    ad_type = AutoForwardDiff()
)
sol = solve(prob, LBFGS())

55 For fitting multiple models to the same dataset:

models = Dict(
    Gent => ComponentVector(
        μ=240e-3,
        J_m=80.0
    ),
    EdwardVilgis => ComponentVector(
        Ns=0.10,
        Nc=0.20,
        α=0.001,
        η=0.001
    ),
    NeoHookean => ComponentVector(
        μ=200e-3
    ),
    Bada => ComponentVector(
        C1=0.1237,
        C2=0.0424,
        C3=7.84e-5,
        K1=0.0168,
        α=0.9,
        β=0.68,
        ζ=3.015
    )
)

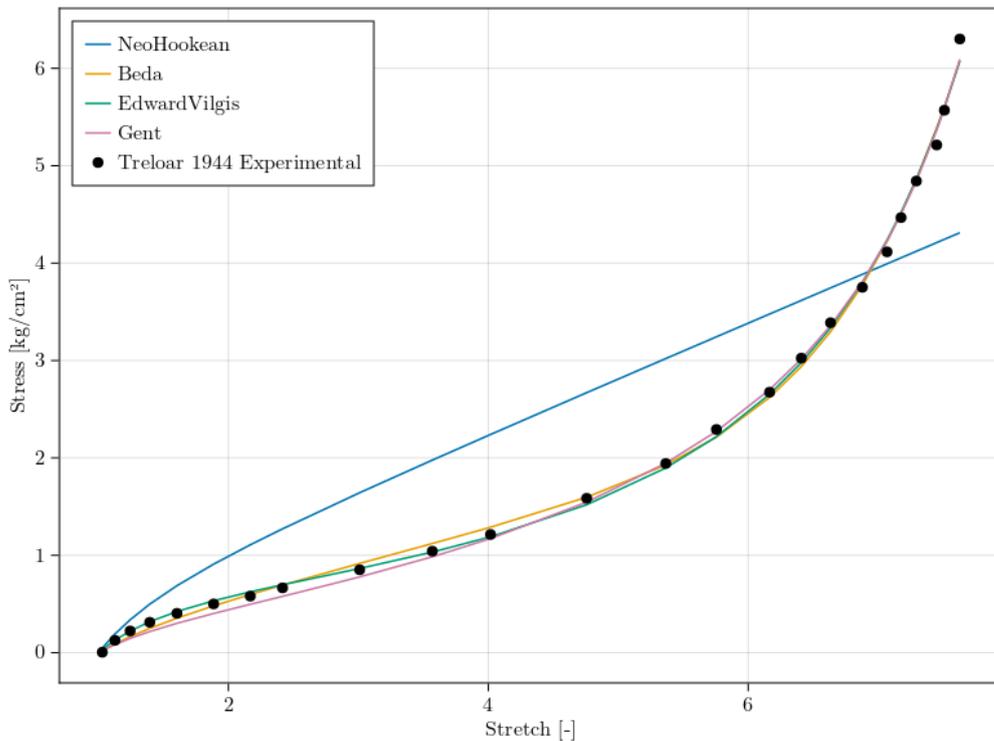
sol = Dict{Any, SciMLSolution}()
for (ψ, p_0) in models
    HEProblem = HyperelasticProblem(
        ψ(),
        treloar_data,
        p_0,
        ad_type = AutoForwardDiff()

```

```

)
sol[ψ] = solve(HEProblem, NelderMead())
end
56 To predict the reponse of a model to a provided dataset and parameters, a predict function
57 is provided:
f = Figure()
ax = Axis(f[1,1])
for (ψ, p) in sol
    pred = predict(
        ψ(),
        treloar_data,
        p.u,
        ad_type = AutoForwardDiff()
    )
    lines!(
        ax,
        getindex.(pred.data.λ, 1),
        getindex.(pred.data.s, 1),
        label=string(ψ)
    )
end
scatter!(ax,
    getindex.(treloar_data.data.λ, 1),
    getindex.(treloar_data.data.s, 1),
    label = "Treloar 1944 Experimental",
    color = :black
)
axislegend(position = :lt)

```



58

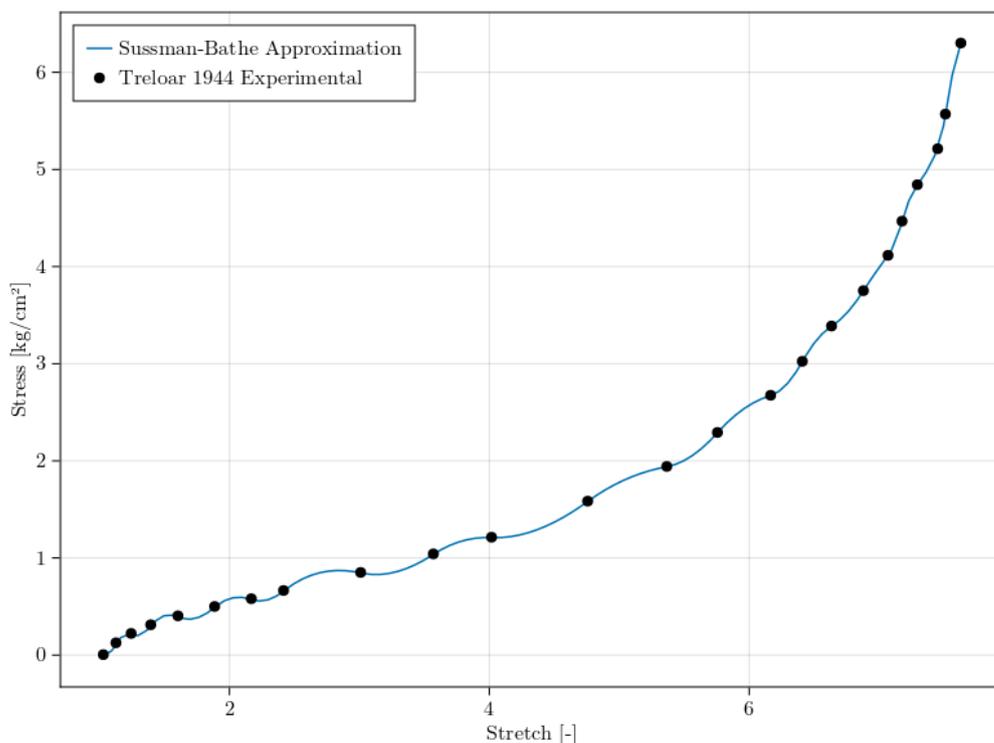
59 While the majority of the models provided by Hyperelastics.jl are based on closed form
60 strain energy density functions, a selection of data-driven models are provided. For example,
61 the SussmanBathe model is created with:

```
using DataInterpolations
ψ = SussmanBathe(treloar_data, k=4, interpolant = QuadraticSpline)
λ_1 = range(extrema(getindex.(treloar_data.data.λ, 1))..., length = 100)
uniaxial_prediction = HyperelasticUniaxialTest(λ_1, name = "Prediction")
pred = predict(ψ, uniaxial_prediction, [])
λ_hat_1 = getindex.(treloar_data.data.λ, 1)
s_1 = getindex.(treloar_data.data.s, 1)
λ_hat_1 = getindex.(pred.data.λ, 1)
s_hat_1 = getindex.(pred.data.s, 1)

f, ax, p = lines(
    λ_hat_1,
    s_hat_1,
    label = "Sussman-Bathe Approximation"
)

scatter!(
    ax,
    λ_1,
    s_1,
    label = "Treloar 1944 Experimental",
    color = :black
)

axislegend(position = :lt)
```



62

63 **Availability**

64 Hyperelastics.jl can be found on [github](#).

65 **Acknowledgements**

66 The TRACER Lab is supported by the School of Engineering and the Center for Engineering
67 Research and Education (CERE) at Liberty University.

68 **References**

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